

Does the “AI” in AI–REML stand for Artificial Intelligence?

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Does the “AI” in AI–REML stand for Artificial Intelligence?

What will I talk about?

- Introduction
- Mixed Models
- REML
- Alternative Estimators
- Computational Shortcuts
- AI-REML

Does the “AI” in AI-REML stand for Artificial Intelligence?

- Short example
- Summary

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Introduction

- Some of the many challenges facing Animal Breeders
 - Analysis of large messy data sets
 - Increasingly complex models
 - Computationally intensive procedures
- Larger and faster computers
 - If you wait long enough
 - There will always be a larger problem
- Computing strategies

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- Most bang for the cycle?
- Several methods of obtaining REML estimates
- Sparse matrix techniques
- Reduced animal model

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Mixed Models

$$y = X\beta + Zu + e$$

$$\begin{pmatrix} u \\ e \end{pmatrix} \sim \mathcal{N} \left[\begin{pmatrix} \mathbf{0} \\ \mathbf{0} \end{pmatrix}, \begin{pmatrix} G & \mathbf{0} \\ \mathbf{0} & R \end{pmatrix} \right]$$

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Variance Components

$$\begin{pmatrix} \mathbf{X}'\mathbf{R}^{-1}\mathbf{X} & \mathbf{X}'\mathbf{R}^{-1}\mathbf{Z} \\ \mathbf{Z}'\mathbf{R}^{-1}\mathbf{X} & \mathbf{Z}'\mathbf{R}^{-1}\mathbf{Z} + \mathbf{G}^{-1} \end{pmatrix} \begin{pmatrix} \hat{\boldsymbol{\beta}} \\ \hat{\mathbf{u}} \end{pmatrix} = \begin{pmatrix} \mathbf{X}'\mathbf{R}^{-1}\mathbf{y} \\ \mathbf{Z}'\mathbf{R}^{-1}\mathbf{y} \end{pmatrix}$$

- \mathbf{G} and \mathbf{R} need to be estimated
- Function of a set of variance components $\boldsymbol{\sigma}$

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REML

- Restricted/Residual Maximum Likelihood
- Find the set of parameters which maximize the likelihood of the residuals

Residuals $\mathbf{K}'\mathbf{y}$

$$L(\mathbf{K}'\mathbf{y}; \boldsymbol{\sigma}) = -\frac{1}{2}[\ln |\mathbf{V}| + \ln |\mathbf{X}'\mathbf{V}^{-1}\mathbf{X}| + \mathbf{y}'\mathbf{P}\mathbf{y}]$$

where

$$\mathbf{P} = \mathbf{V}^{-1} - \mathbf{V}^{-1}\mathbf{X}(\mathbf{X}'\mathbf{V}^{-1}\mathbf{X})^{-1}\mathbf{X}'\mathbf{V}^{-1}$$

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Alternative Estimators

- DF-REML
 - Evaluate the log-likelihood at many different places until a maximum is found
- EM-REML
 - If we had u and e it would be easy
 - Take the expected value of “ u ” and “ e ” given y and σ and maximize
- Derivative based methods

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Derivative based methods

$$L(\mathbf{K}'\mathbf{y}; \boldsymbol{\sigma}) = -\frac{1}{2}[\ln |\mathbf{V}| + \ln |\mathbf{X}'\mathbf{V}^{-1}\mathbf{X}| + \mathbf{y}'\mathbf{P}\mathbf{y}]$$

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Score function

$$\frac{\partial L}{\partial \sigma_i} = -\frac{1}{2} \left[\text{tr} \left(\mathbf{P} \frac{\partial \mathbf{V}}{\partial \sigma_i} \right) - \mathbf{y}' \mathbf{P} \frac{\partial \mathbf{V}}{\partial \sigma_i} \mathbf{P} \mathbf{y} \right]$$

Set this equal to zero and solve.

$$\frac{\partial \mathbf{V}}{\partial \sigma_i} = \mathbf{Z} \frac{\partial \mathbf{G}}{\partial \sigma_i} \mathbf{Z}' + \frac{\partial \mathbf{R}}{\partial \sigma_i}$$

$$\begin{aligned} \frac{\partial \mathbf{V}}{\partial \sigma_i} \mathbf{P} \mathbf{y} &= \mathbf{Z} \frac{\partial \mathbf{G}}{\partial \sigma_i} \mathbf{G}^{-1} \hat{\mathbf{u}} \\ &\quad + \frac{\partial \mathbf{R}}{\partial \sigma_i} \mathbf{R}^{-1} \hat{\mathbf{e}} \end{aligned}$$

$$\begin{aligned} \mathbf{y}' \mathbf{P} \frac{\partial \mathbf{V}}{\partial \sigma_i} \mathbf{P} \mathbf{y} &= \hat{\mathbf{u}}' \mathbf{G}^{-1} \frac{\partial \mathbf{G}}{\partial \sigma_i} \mathbf{G}^{-1} \hat{\mathbf{u}} \\ &\quad + \hat{\mathbf{e}}' \mathbf{R}^{-1} \frac{\partial \mathbf{R}}{\partial \sigma_i} \mathbf{R}^{-1} \hat{\mathbf{e}} \end{aligned}$$

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$$\begin{aligned}
\text{tr}\left(\mathbf{P}\frac{\partial\mathbf{V}}{\partial\sigma_i}\right) &= \text{tr}\left(\mathbf{P}\frac{\partial\mathbf{R}}{\partial\sigma_i} + \mathbf{P}\mathbf{Z}\frac{\partial\mathbf{G}}{\partial\sigma_i}\mathbf{Z}'\right) \\
&= \text{tr}\left([\mathbf{R}^{-1} - \mathbf{R}^{-1}\text{var}(\hat{\mathbf{e}} - \mathbf{e})\mathbf{R}^{-1}]\frac{\partial\mathbf{R}}{\partial\sigma_i}\right) \\
&\quad + \text{tr}\left([\mathbf{G}^{-1} - \mathbf{G}^{-1}\text{var}(\hat{\mathbf{u}} - \mathbf{u})\mathbf{G}^{-1}]\frac{\partial\mathbf{G}}{\partial\sigma_i}\right)
\end{aligned}$$

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Information matrix

- Newton Raphson

$$-\left(\frac{\partial^2 L}{\partial \boldsymbol{\sigma} \partial \boldsymbol{\sigma}'}\right) (\Delta \boldsymbol{\sigma}) = \frac{\partial L}{\partial \boldsymbol{\sigma}}$$

- Fisher's method of Scoring

$$-\mathbb{E}\left(\frac{\partial^2 L}{\partial \boldsymbol{\sigma} \partial \boldsymbol{\sigma}'}\right) (\Delta \boldsymbol{\sigma}) = \frac{\partial L}{\partial \boldsymbol{\sigma}}$$

- Assuming the second partials of V with respect to the variance components are zero.

$$\frac{\partial^2 L}{\partial \boldsymbol{\sigma} \partial \boldsymbol{\sigma}'} = -\frac{1}{2} \left[-\text{tr} \left(\mathbf{P} \frac{\partial \mathbf{V}}{\partial \sigma_i} \mathbf{P} \frac{\partial \mathbf{V}}{\partial \sigma_j} \right) + 2\mathbf{y}' \mathbf{P} \frac{\partial \mathbf{V}}{\partial \sigma_i} \mathbf{P} \frac{\partial \mathbf{V}}{\partial \sigma_j} \mathbf{P} \mathbf{y} \right]$$

$$\mathbb{E} \left[\frac{\partial^2 L}{\partial \boldsymbol{\sigma} \partial \boldsymbol{\sigma}'} \right] = -\frac{1}{2} \left[\text{tr} \left(\mathbf{P} \frac{\partial \mathbf{V}}{\partial \sigma_i} \mathbf{P} \frac{\partial \mathbf{V}}{\partial \sigma_j} \right) \right]$$

- Quadratic form in $\hat{\mathbf{u}}$ and $\hat{\mathbf{e}}$

$$\mathbf{f}_i = \mathbf{Z} \frac{\partial \mathbf{G}}{\partial \sigma_i} \mathbf{G}^{-1} \hat{\mathbf{u}} + \frac{\partial \mathbf{R}}{\partial \sigma_i} \mathbf{R}^{-1} \hat{\mathbf{e}}$$

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- Also involves

$$\text{tr}\left(\mathbf{P} \frac{\partial \mathbf{V}}{\partial \sigma_i} \mathbf{P} \frac{\partial \mathbf{V}}{\partial \sigma_j}\right)$$

- Occurs in NR with a $\frac{1}{2}$ and in FS with a $-\frac{1}{2}$

AI-REML

- Newton Raphson tends to be quicker
- Newton Raphson may go in the wrong direction
 - Information matrix does not have to be positive semi-definite
- Fisher's method of scoring will at least go uphill
 - may also go up the other side
- Both involve a complicated trace

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- If we average them the complicated trace drops out and we are left with a number of quadratic forms to evaluate

Average information

$$-\frac{1}{2} \mathbf{y}' \mathbf{P} \frac{\partial \mathbf{V}}{\partial \sigma_i} \mathbf{P} \frac{\partial \mathbf{V}}{\partial \sigma_j} \mathbf{P} \mathbf{y}$$

- Which after a little simplification reduces to

$$\mathbf{I}_A = \mathbf{F}' \mathbf{P} \mathbf{F}$$

$$\mathbf{F} = \mathbf{Z} \frac{\partial \mathbf{G}}{\partial \sigma} \mathbf{G}^{-1} \hat{\mathbf{u}} + \frac{\partial \mathbf{R}}{\partial \sigma} \mathbf{R}^{-1} \hat{\mathbf{e}}$$

$$\mathbf{I}_A = \mathbf{F}' \mathbf{R}^{-1} \mathbf{F} - \begin{pmatrix} \hat{\boldsymbol{\beta}}_F \\ \hat{\mathbf{u}}_F \end{pmatrix}' \begin{pmatrix} \mathbf{X}' \mathbf{R}^{-1} \mathbf{F} \\ \mathbf{Z}' \mathbf{R}^{-1} \mathbf{F} \end{pmatrix}$$

- \mathbf{I}_A is a positive semi-definite matrix

Algorithm

$$(F'PF)\Delta\sigma = F'Py - \left\{ \text{tr}\left(P\frac{\partial V}{\partial\sigma_i}\right) \right\}$$

- A number of quadratic forms
- Solve the mixed model equations once for the original data, and once for each of the variance components
- Done correctly the subsequent solves are not very expensive computationally

Small Example

- Crimson Clover Example
- Treatment design was a 2^3 Factorial
- Seven replicates each consisting of four plants
- Plants were divided in half with a different treatment applied to each half
- Dependent variable was hard seed percentage

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$$y_{rtp} = rep_r + \tau_t + plant_p(rep)_r + e_{rtp}$$

$$\begin{pmatrix} rep \\ plant \\ e \end{pmatrix} \sim \mathcal{N} \left[\begin{pmatrix} \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \end{pmatrix}, \begin{pmatrix} \mathbf{I}_7 \sigma_r^2 & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{I}_{28} \sigma_p^2 & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{I}_{56} \sigma_e^2 \end{pmatrix} \right]$$

$$\boldsymbol{\sigma} = (\sigma_r^2 \quad \sigma_p^2 \quad \sigma_e^2)$$

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Program

```
sol=lhsi*rhs;  
u1=sol(p+1:p+q1,:);  
u2=sol(p+q1+1:p+q1+q2,:);  
e=y-w*sol;
```

```
f0=e/sig0;  
f1=z1*u1/sig1;  
f2=z2*u2/sig2;  
F=<f0 f1 f2>;
```

```
tr1=sum(diag(lhsi((p+1):(p+q1)),...
```

```

    (p+1):(p+q1)))));
tr2=sum(diag(lhsi((p+q1+1):..
    (p+q1+q2),(p+q1+1):(p+q1+q2)))));
ss1=q1/sig1-(tr1+u1'*u1)/(sig1*sig1);
ss2=q2/sig2-(tr2+u2'*u2)/(sig2*sig2);
ss0=((n-(p+q1+q2))+..
    (tr1/sig1+tr2/sig2))/sig0-..
e'*e/(sig0*sig0);
ss=-.5*<ss0;ss1;ss2>;

Flhs=w'*f/sig0;
fsol=lhsi*Flhs;
Inf=F'*F*(1/sig0)-fsol'*flhs;

```

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```
Inf = .5*Inf;
```

```
ascv = inv(inf)
```

```
delt = ascv*ss
```

```
var = <sig0; sig1; sig2> + delt
```

Results

- Starting with 1, 1, and 1
- Converged after 12 iterations

$$\hat{\sigma}_r^2 = 47 \pm 63$$

$$\hat{\sigma}_p^2 = 184 \pm 74$$

$$\hat{\sigma}_e^2 = 89 \pm 27$$

Summary

- The “AI” in AI-REML stands for average information
- Uses the average of the observed and expected information
- Computationally less expensive/iteration than either NR or FS
- Appears to converge fairly quickly
- Unlike NR it will always head in a “reasonable” direction
- Generalizes easily to the case when $V \neq \sum V_i \sigma_i$